

从直角坐标到球坐标的拉普拉斯算子

在直角坐标中，拉普拉斯算子定义为：

$$\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$$

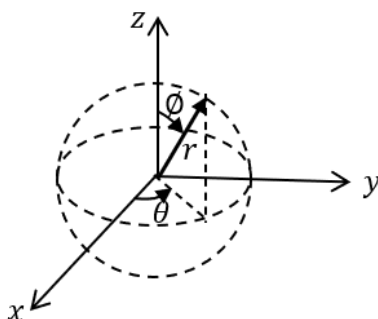


图1: 球坐标示意图.

如图 1 所示，引入球坐标：

$$\begin{aligned}x &= r \sin \phi \cos \theta \\y &= r \sin \phi \sin \theta \\z &= r \cos \phi\end{aligned}$$

因为

$$\begin{aligned}r &= \sqrt{x^2 + y^2 + z^2} \\ \theta &= \arctan(y/x) \\ \phi &= \arccos(z/r)\end{aligned}$$

所以

$$\begin{aligned}
\frac{\partial r}{\partial x} &= x/r = \sin\phi\cos\theta \\
\frac{\partial r}{\partial y} &= y/r = \sin\phi\sin\theta \\
\frac{\partial r}{\partial z} &= z/r = \cos\phi \\
\frac{\partial \theta}{\partial x} &= -\frac{\sin\theta}{r\sin\phi} \\
\frac{\partial \theta}{\partial y} &= \frac{\cos\theta}{r\sin\phi} \\
\frac{\partial \theta}{\partial z} &= 0 \\
\frac{\partial \phi}{\partial x} &= \frac{1}{r}\cos\phi\cos\theta \\
\frac{\partial \phi}{\partial y} &= \frac{1}{r}\cos\phi\sin\theta \\
\frac{\partial \phi}{\partial z} &= -\frac{\sin\phi}{r}
\end{aligned}$$

由此,

$$\begin{aligned}
\frac{\partial f}{\partial x} &= \frac{\partial f}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial f}{\partial \theta} \frac{\partial \theta}{\partial x} + \frac{\partial f}{\partial \phi} \frac{\partial \phi}{\partial x} \\
&= \sin\phi\cos\theta \frac{\partial f}{\partial r} - \frac{\sin\theta}{r\sin\phi} \frac{\partial f}{\partial \theta} + \frac{1}{r}\cos\phi\cos\theta \frac{\partial f}{\partial \phi}
\end{aligned}$$

$$\frac{\partial^2 f}{\partial x^2} = \left[\sin\phi\cos\theta \frac{\partial}{\partial r} - \frac{\sin\theta}{r\sin\phi} \frac{\partial}{\partial \theta} + \frac{1}{r}\cos\phi\cos\theta \frac{\partial}{\partial \phi} \right] \left[\sin\phi\cos\theta \frac{\partial f}{\partial r} - \frac{\sin\theta}{r\sin\phi} \frac{\partial f}{\partial \theta} + \frac{1}{r}\cos\phi\cos\theta \frac{\partial f}{\partial \phi} \right] \quad (1)$$

类似地,

$$\begin{aligned}
\frac{\partial f}{\partial y} &= \frac{\partial f}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial f}{\partial \theta} \frac{\partial \theta}{\partial y} + \frac{\partial f}{\partial \phi} \frac{\partial \phi}{\partial y} \\
&= \sin\phi\sin\theta \frac{\partial f}{\partial r} + \frac{\cos\theta}{r\sin\phi} \frac{\partial f}{\partial \theta} + \frac{1}{r}\cos\phi\sin\theta \frac{\partial f}{\partial \phi}
\end{aligned}$$

$$\frac{\partial^2 f}{\partial y^2} = \left[\sin\phi\sin\theta \frac{\partial}{\partial r} + \frac{\cos\theta}{r\sin\phi} \frac{\partial}{\partial \theta} + \frac{1}{r}\cos\phi\sin\theta \frac{\partial}{\partial \phi} \right] \left[\sin\phi\sin\theta \frac{\partial f}{\partial r} + \frac{\cos\theta}{r\sin\phi} \frac{\partial f}{\partial \theta} + \frac{1}{r}\cos\phi\sin\theta \frac{\partial f}{\partial \phi} \right] \quad (2)$$

$$\begin{aligned}\frac{\partial f}{\partial z} &= \frac{\partial f}{\partial r} \frac{\partial r}{\partial z} + \frac{\partial f}{\partial \theta} \frac{\partial \theta}{\partial z} + \frac{\partial f}{\partial \phi} \frac{\partial \phi}{\partial z} \\ &= \cos\phi \frac{\partial f}{\partial r} - \frac{1}{r} \sin\phi \frac{\partial f}{\partial \phi}\end{aligned}$$

$$\frac{\partial^2 f}{\partial z^2} = \left[\cos\phi \frac{\partial}{\partial r} - \frac{1}{r} \sin\phi \frac{\partial}{\partial \phi} \right] \left[\cos\phi \frac{\partial f}{\partial r} - \frac{1}{r} \sin\phi \frac{\partial f}{\partial \phi} \right] \quad (3)$$

将 (1)、(2) 和 (3) 相加并简化,可以得到球坐标中的拉普拉斯算子:

$$\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} = \frac{1}{r^2} \frac{\partial}{\partial r} \left[r^2 \frac{\partial f}{\partial r} \right] + \frac{1}{r^2 \sin\phi} \frac{\partial}{\partial \phi} \left[\sin\phi \frac{\partial f}{\partial \phi} \right] + \frac{1}{r^2 \sin^2(\phi)} \frac{\partial^2 f}{\partial \theta^2} \quad (4)$$